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# JavaOne<sup>SM</sup>

Save the Planet!  
Go Green  
using Java technology

Cory Sharp  
Sentilla Corporation







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## Featured Projects



### LCD Display Driver

*by Jason*

A driver for the BPK-216 LCD display.



### Fridge Monitor

*by cmerlin*

Keep Cool



### Check Gmail with JCreates

*by dan*

Gmail, in Mote Form



### Environmental Sensors

*by andrew*

Environmental Sensors



### Wireless Pedometer

*by andrew*

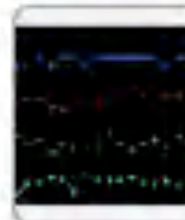
Count your steps and report back.



### Pong

*by dan*

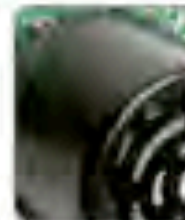
It's Pong, in Pong Form



### JCreate Charting

*by dan*

Plot mote data with using processing.



### Ultrasonic Distance Finder

*by dan*

A Maxbotix LV-EZ4 attached to a JCreate and visualized via Processing



### Bathroom Monitor

*by andrew*

Know if the bathroom is in use before you walk all the way over there



### Roll a dice

*by andreas*

Shake your mote to roll the dice...



### Ever lost someone or something?

*by andrew*

This project shows how to use the JCreates to find each other



### Another Coaster Application

*by cmerlin*

Hang on to your motes!

## WELCOME

Sentilla Labs showcases the latest, coolest pervasive computing applications built by developers using Sentilla's technology. Share your ideas and be inspired by others.

## PERK

Perk is Sentilla's all-in-one pervasive computing kit. Every project on Sentilla Labs was built using Perk. To start building your own application grab a **Perk** kit today.

## TAGS

**5V alarm boost** charting  
 dice display distance  
 drinking energy environment  
 fitness fridge **game** gmail  
 graph **green** humidity java  
**jcreate** jtable lcd mail  
 maxbotix notification printing  
**processing** random  
 reed switch RSSI  
**security** sensor swing  
**temperature** time series  
 Tracking



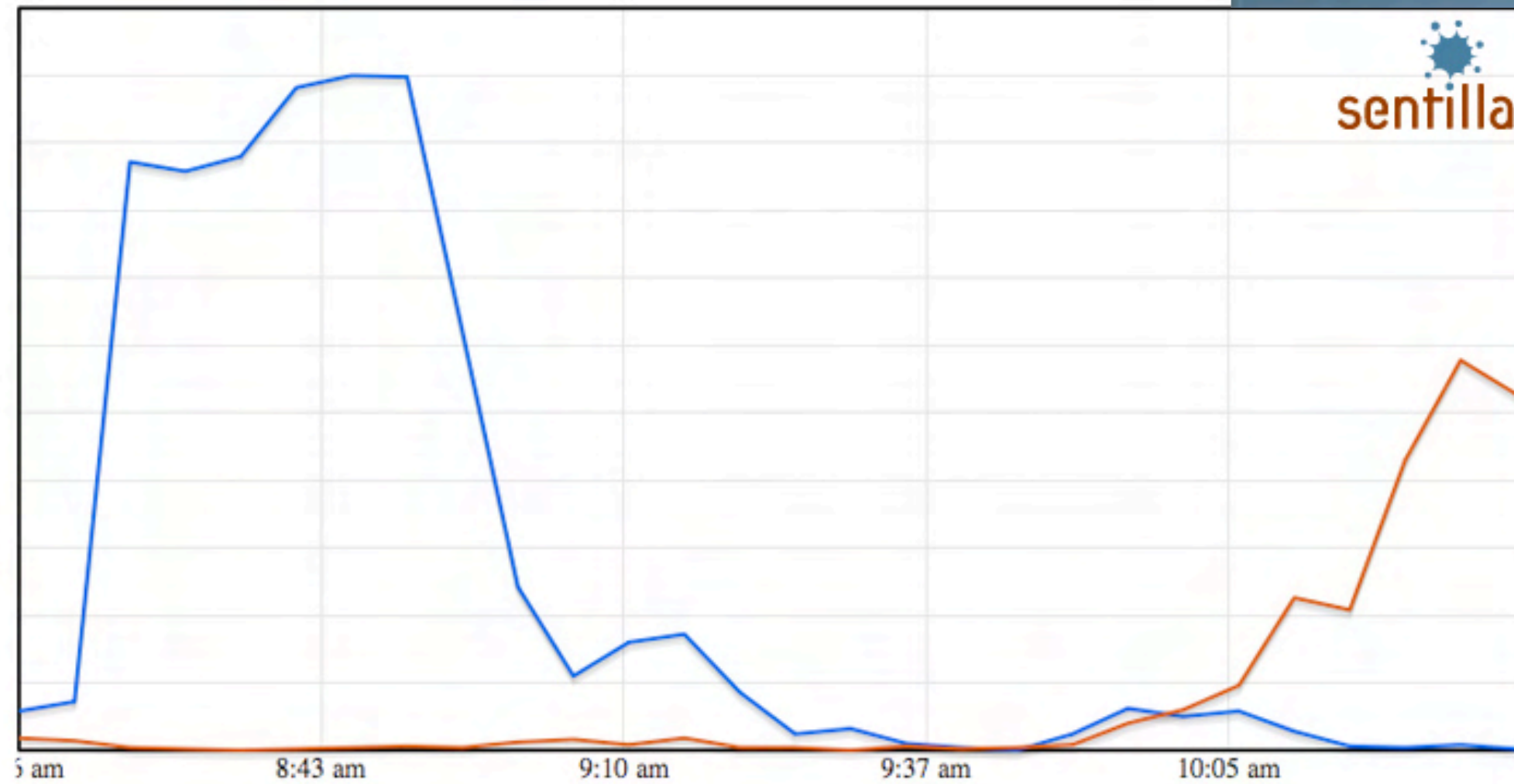
sentilla.

## Sun General Session



**Rich Green**  
Executive Vice President, Software  
Sun Microsystems, Inc.

**Java + YOU**  
Tuesday, May 6th  
8:30 am - 10:30 am Halls B & C



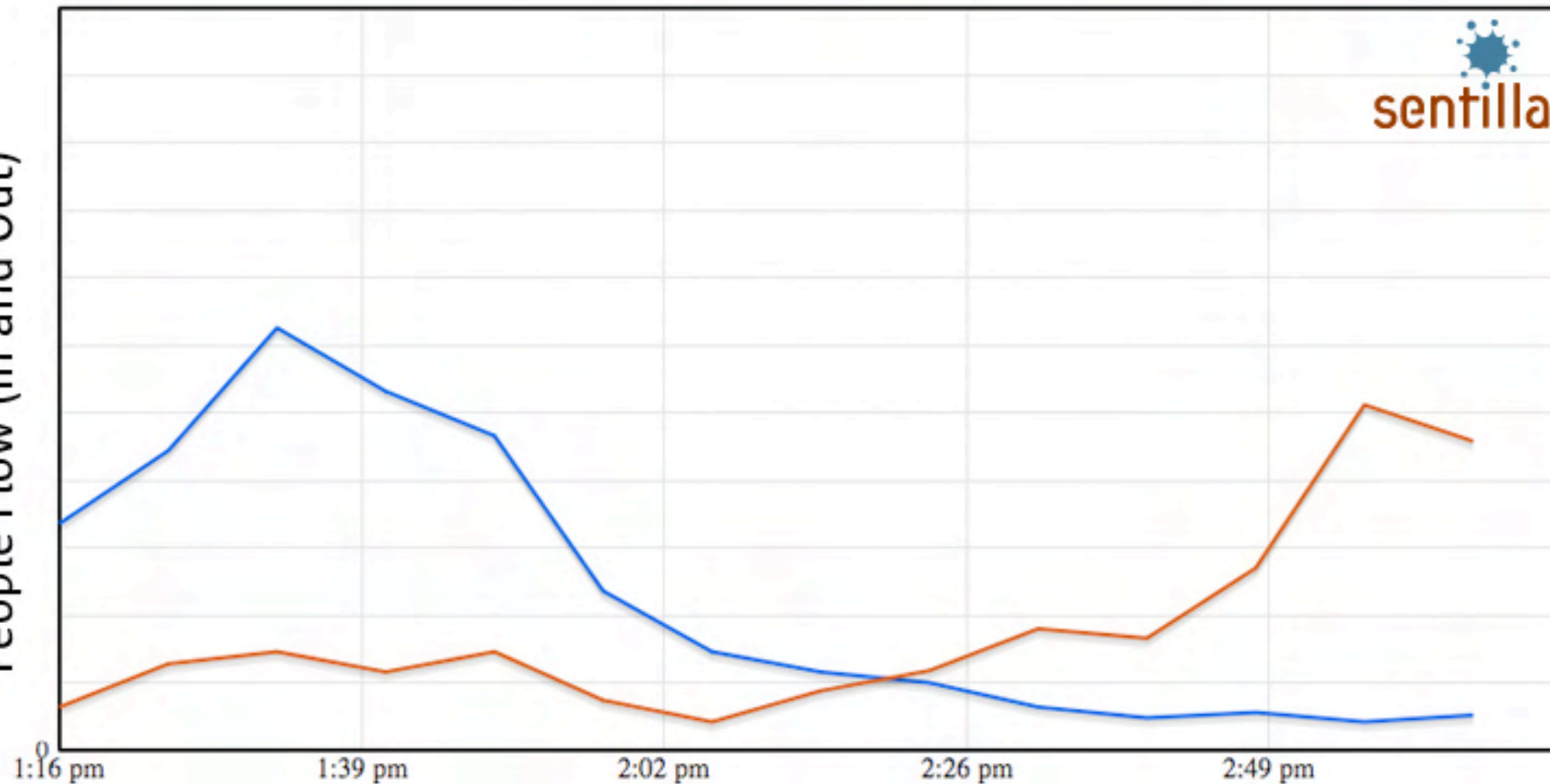
sentilla.

## Sun General Session



**Robert Brewin**  
Distinguished Engineer and Chief Technology Officer, Software  
Sun Microsystems, Inc.

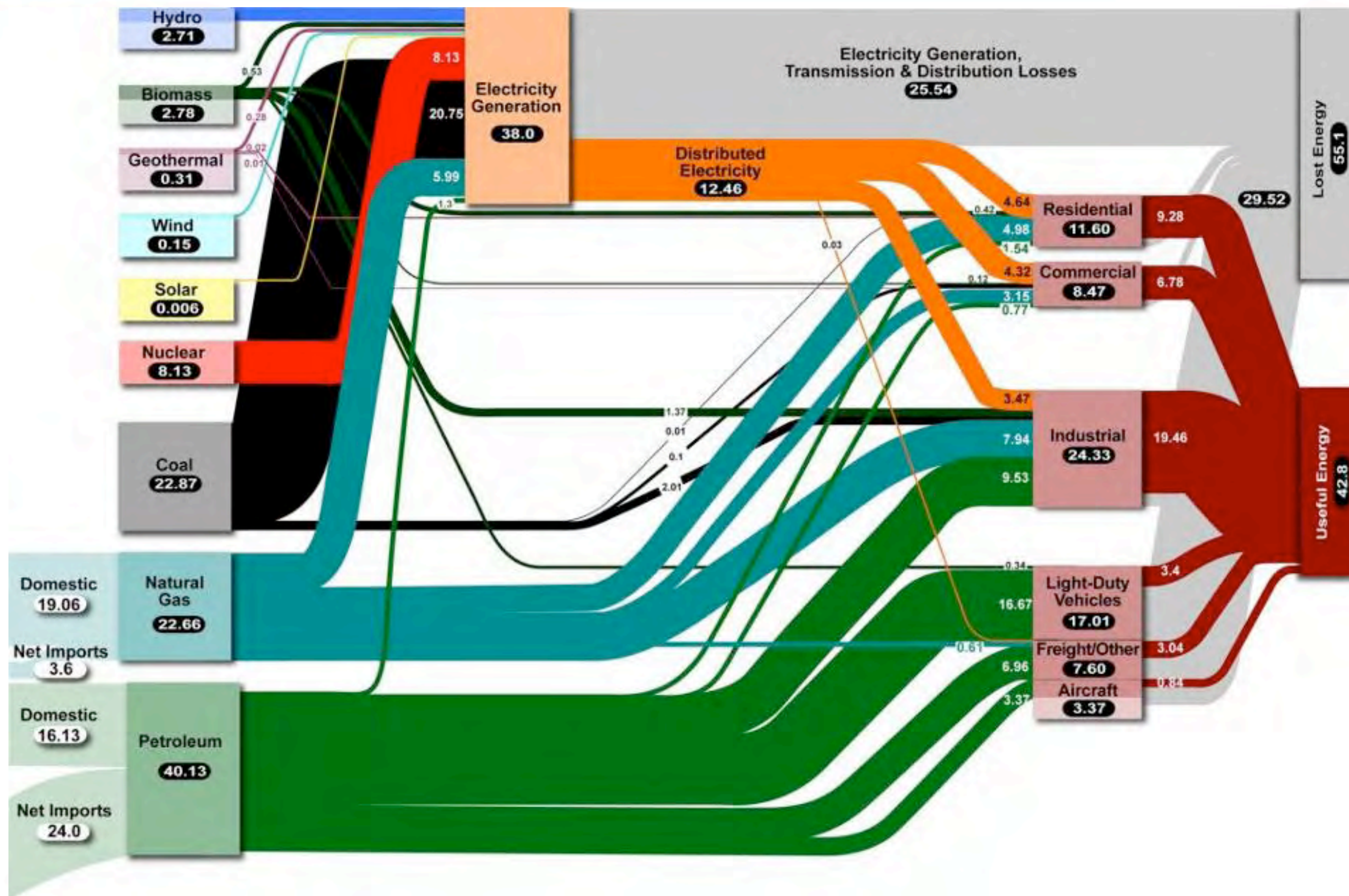
**Java-Centricity: Leveraging Java Technology at the hub of your Digital Life**  
Tuesday, May 6th  
1:30 pm - 3:00 pm Halls B & C

















**ELECTRIC ACCOUNT DETAIL**

Service ID #: 2013989307  
Rate Schedule: E1 TB Residential Service  
Billing Days: 32 days

Serial	Rotating Outage Blk	Meter #	Prior Meter Read	Current Meter Read	Difference	Meter Constant	Usage
G	50	32L596	47,315	47,602	287	1	287 Kwh

Charges

**08/02/2008 - 09/02/2008**

Electric Charges \$33.51

Baseline Quantity 265.60000 Kwh

Baseline Usage 265.60000 Kwh @ \$0.11559

101-130% of Baseline 21.40000 Kwh @ \$0.13142

Net Charges \$33.51



# 100+ Watts

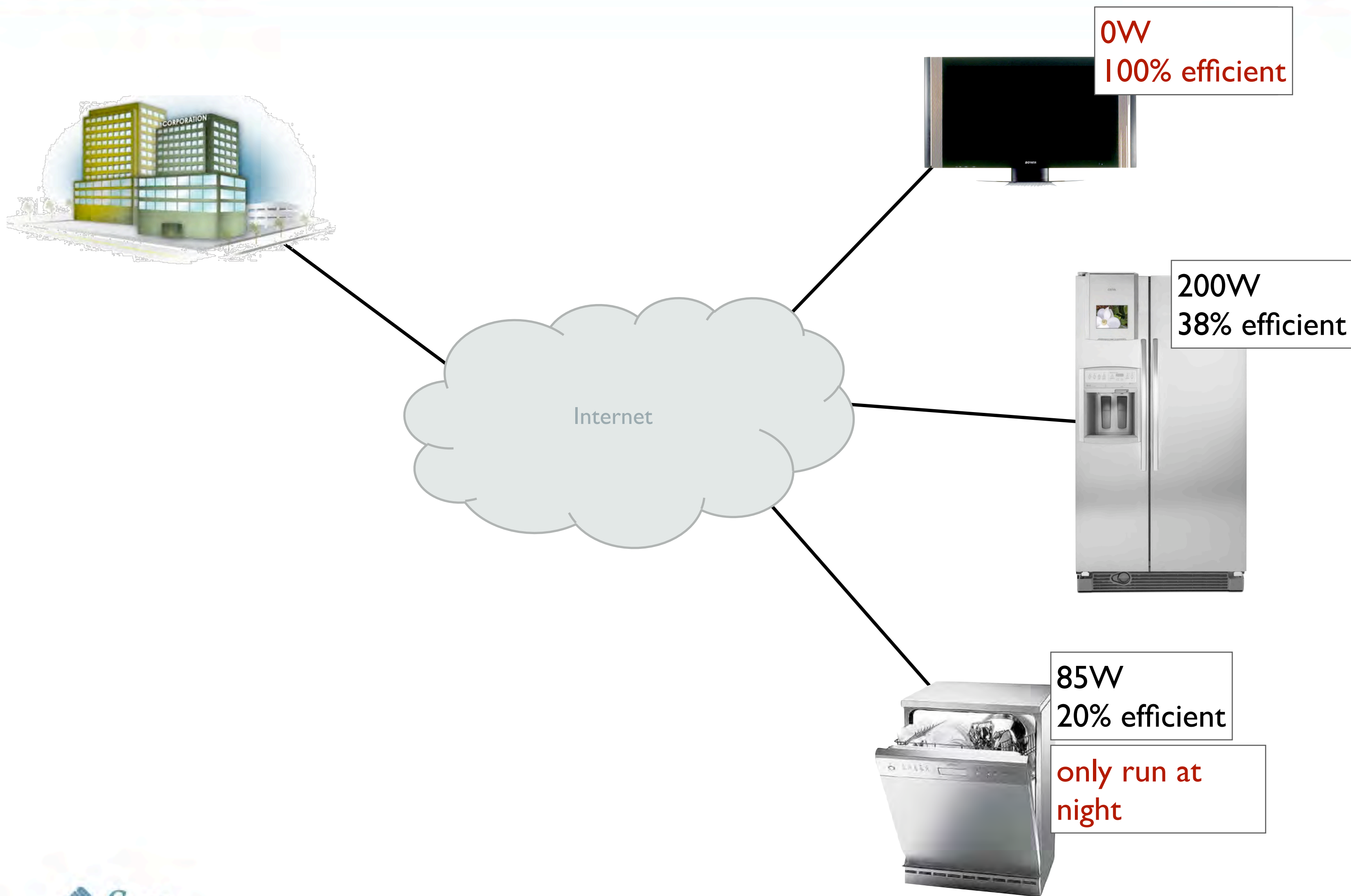




# 10 Watts (!!!)











## ELECTRIC ACCOUNT DETAIL

Service ID #: 2013989307  
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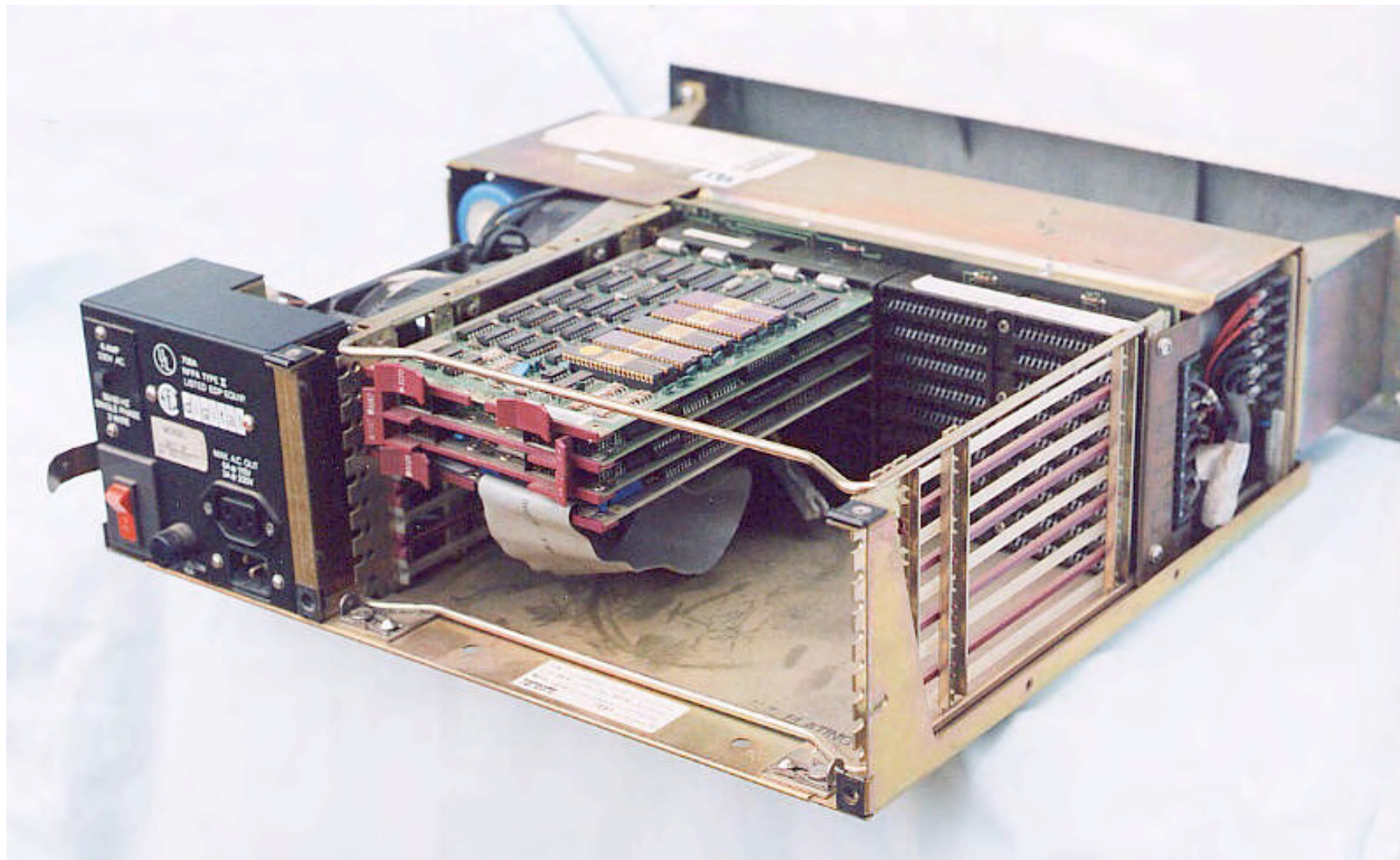
Serial	Rotating Outage Blk	Meter #	Prior Meter Read	Current Meter Read	Difference	Meter Constant	Usage
G	50	32L596	47,315	47,602	287	1	287 Kwh

### Charges

Television	120.3 Kwh	\$13.83
Refrigerator	50.2 Kwh	\$5.77
Dishwasher	10.1 Kwh	\$1.16
Computer	12.2 Kwh	\$1.40
Clothes Dryer	35.2 Kwh	\$4.05
Not Controlled	59.0 Kwh	\$6.79



## Evolution



**PDP-11**  
16-bit  
64 kB  
c. 1970

**Mote**  
16-bit  
48 kB  
c. 2004



**Mote**  
32-bit  
512 kB  
c. 2009



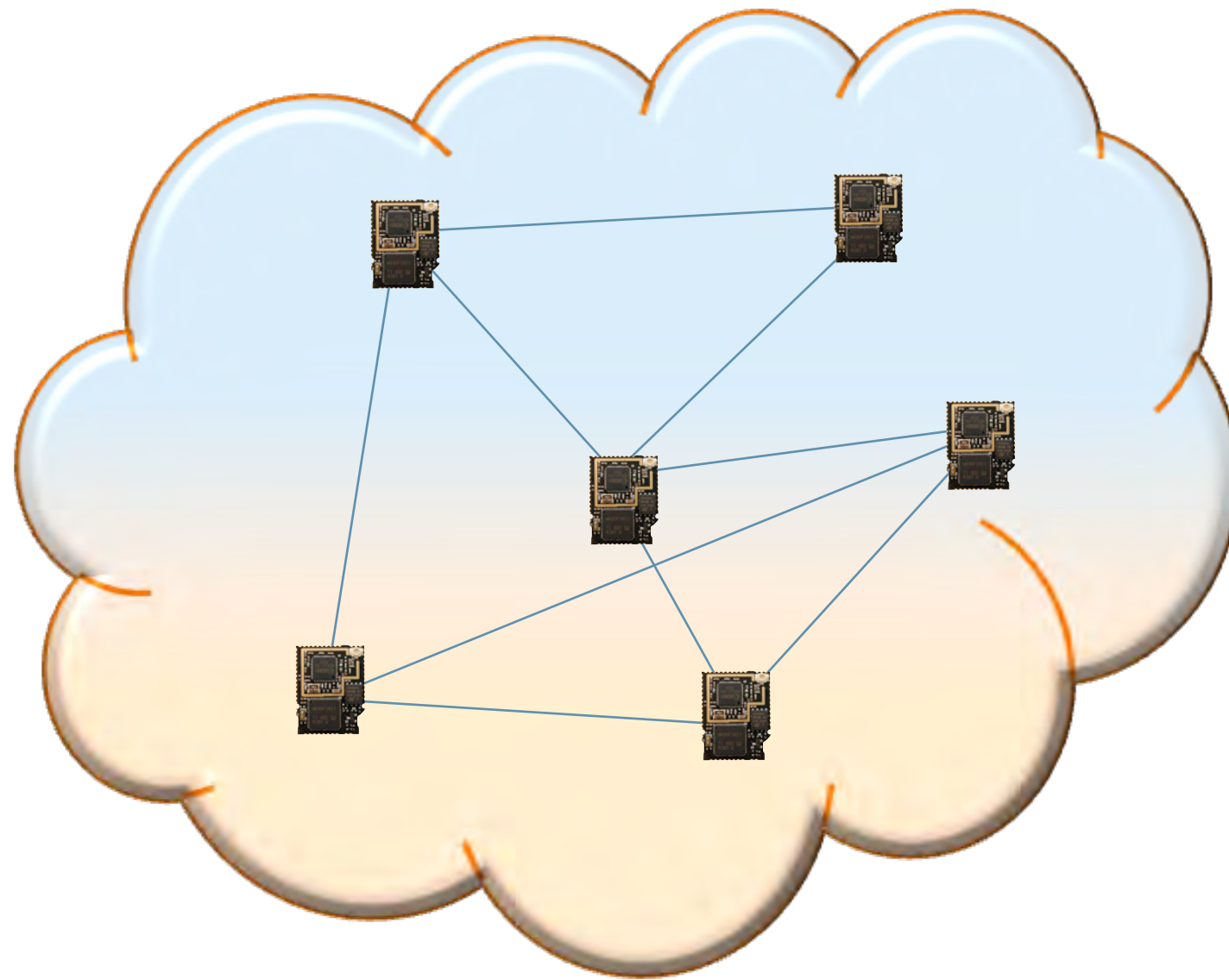
(Images to scale)





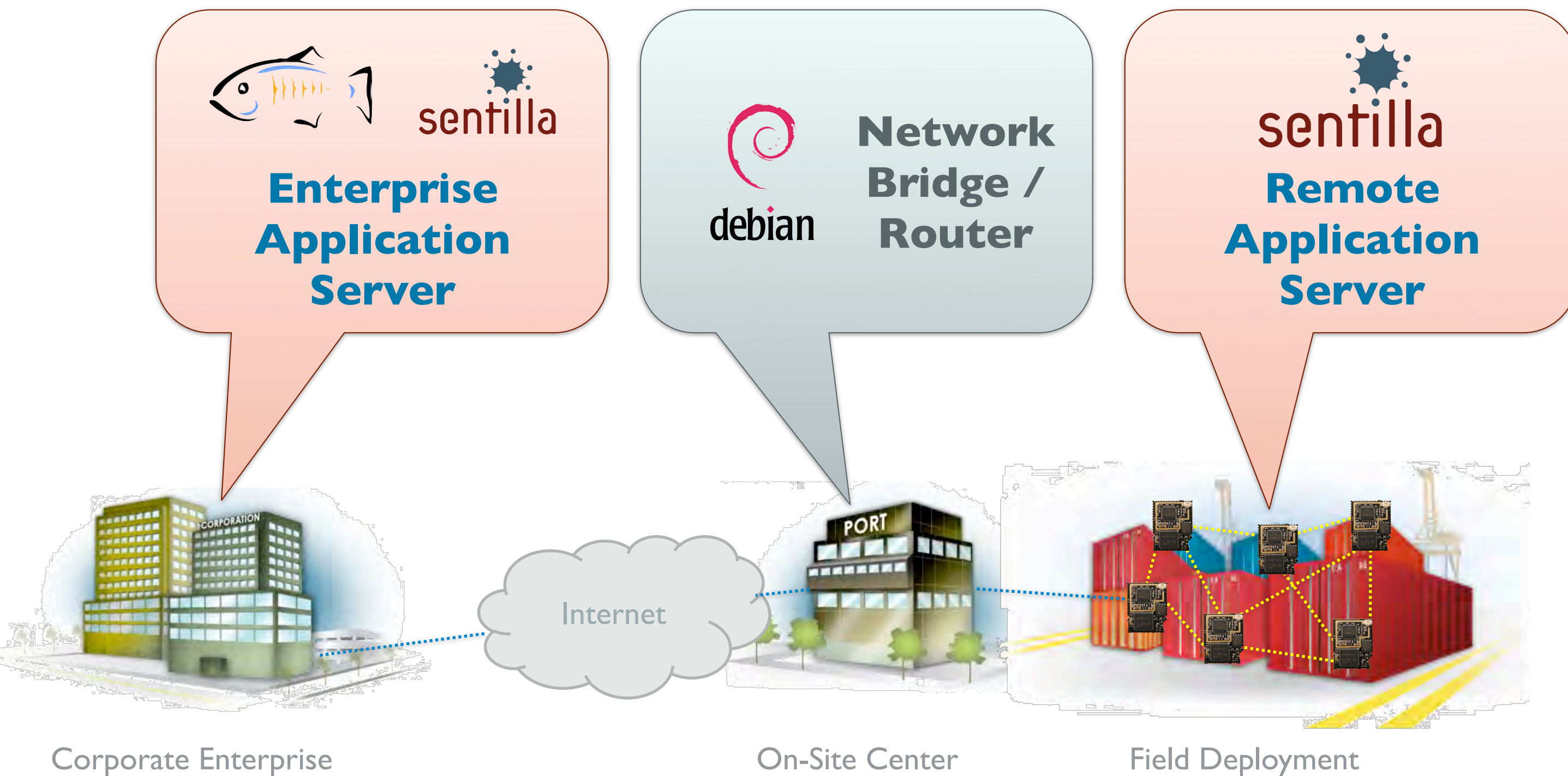


# Physical Computing Cloud



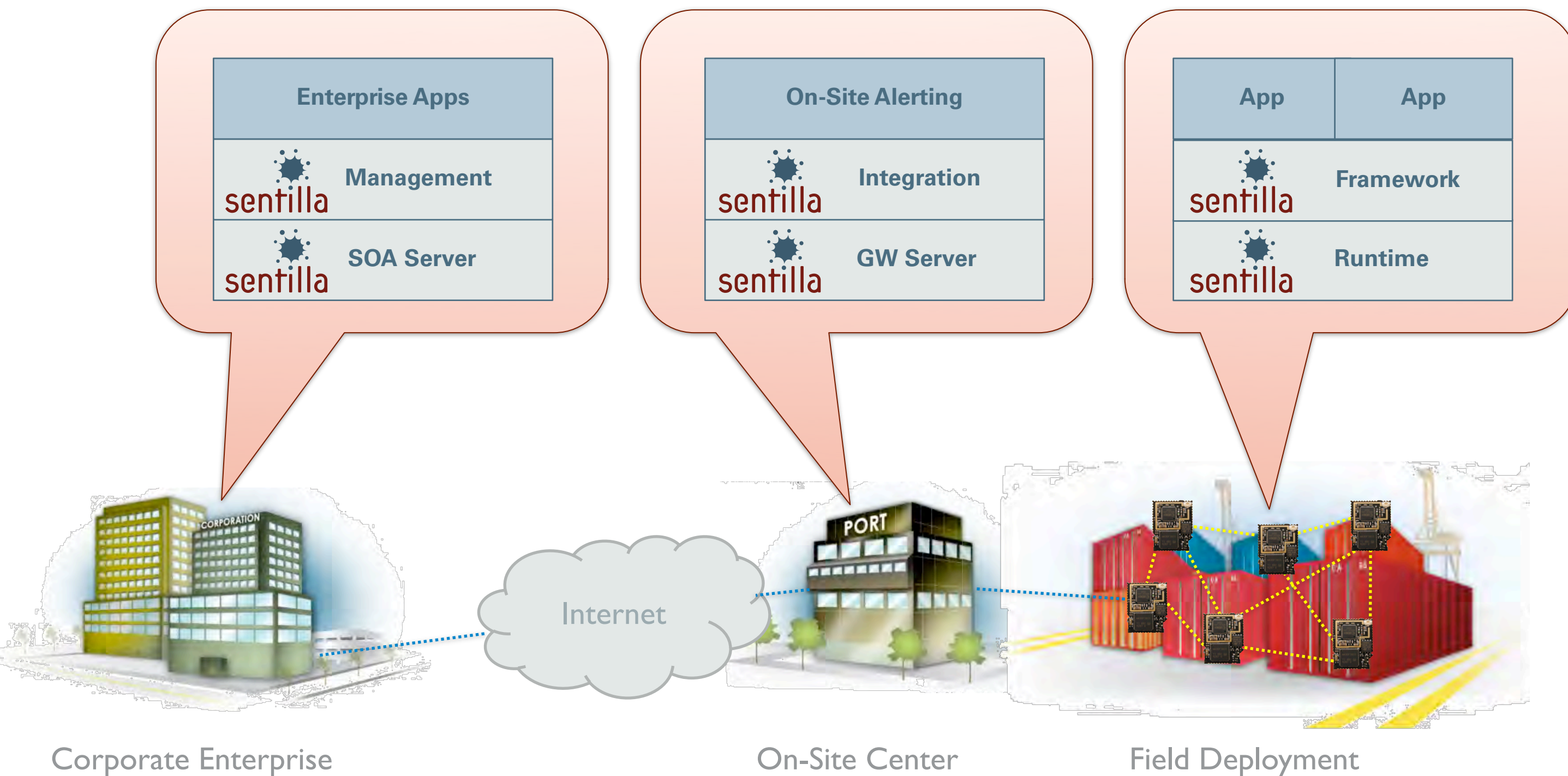


## Unified Framework for Applications



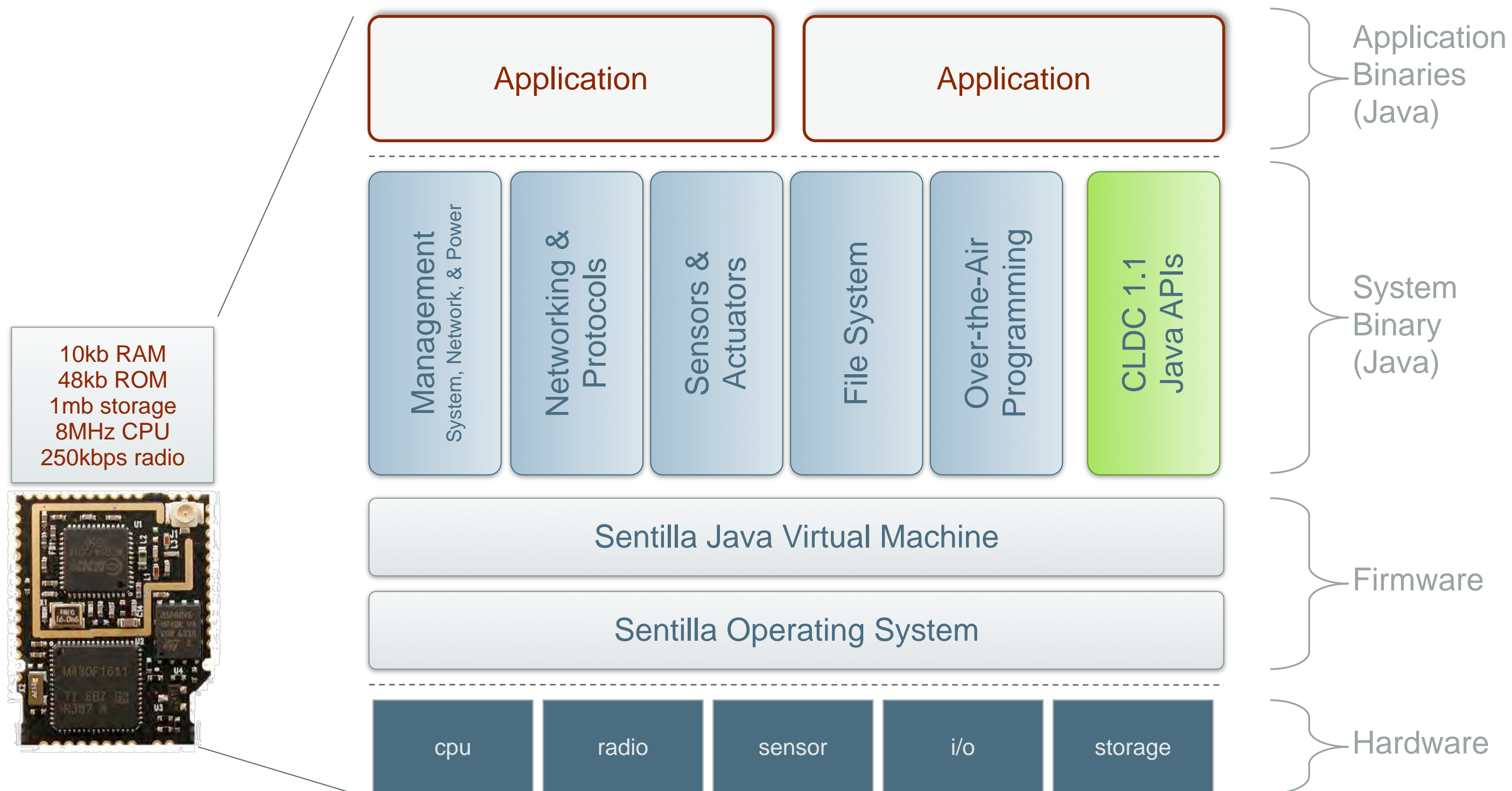


## Sentilla Software Platform Overview



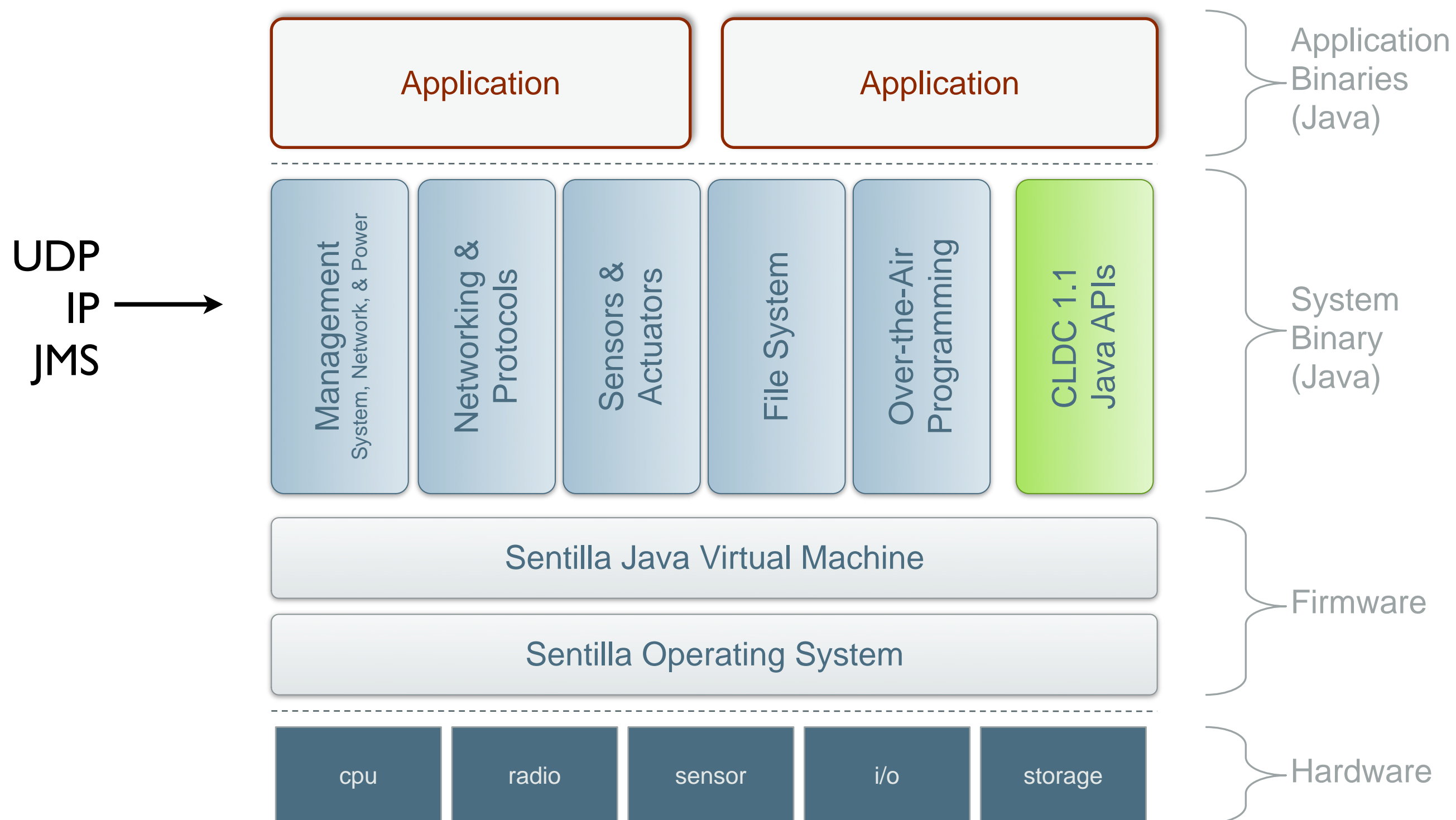


## Sentilla Mote Software Architecture

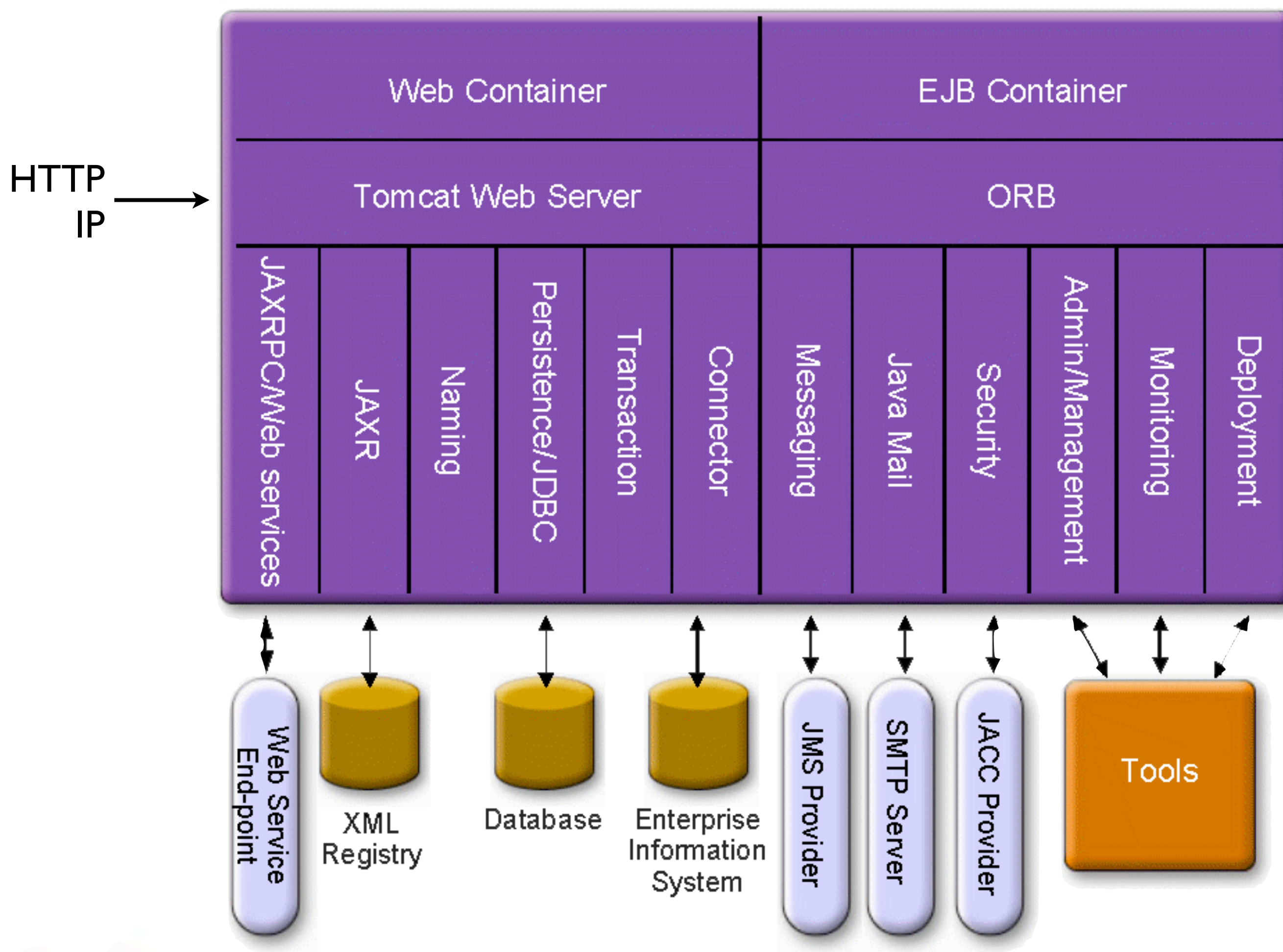




## Sentilla Mote Software Architecture









# Code Comparison

```
import com.sentilla.io.*;
import com.sentilla.system.*;
import javax.measure.*;
```

```
public class SensorApp {
```

```
    public static class SensorMessage implements Serializable {
        public long address;
        public Measurable<Temperature> value;
    }
```

```
    public static void motemain() {
        Sensor<Temperature> temp =
            SensorDriver.create("mcTemp", Temperature.class);
        Sender sender = SenderDriver.create("collect");
        SensorMessage msg = new SensorMessage();
        msg.address = PropertyDriver.opn("mac64").readLong();
        while (true) {
            msg.value = temp.read();
            if (msg.value.doubleValue(SI.CELSIUS) > (double)50) {
                sender.send(msg);
            }
        }
    }
```

```
#ifndef MULTIHOPE_OSCILLOSCOPE_H
#define MULTIHOPE_OSCILLOSCOPE_H
enum {
    /* Number of readings per message. If you increase this, you may have to
    increase the message_t size. */
    NREADINGS = 5,
    DEFAULT_INTERVAL = 1024,
    AM_OSCILLOSCOPE = 0x93
};
typedef nx_struct oscilloscope {
    nx_uint16_t version; /* Version of the interval. */
    nx_uint16_t interval; /* Sampling period. */
    nx_uint16_t id; /* Note id of sending mote. */
    nx_uint16_t count; /* The readings are samples count * NREADINGS onwards */
    nx_uint16_t readings[NREADINGS];
} oscilloscope_t;
#endif

configuration MultiHopOscilloscopeAppC {
    implementation {
        components MainC, MultiHopOscilloscopeC, LedsC, new TimerMilliC(),
            new DemoSensorC() as Sensor;
        MultiHopOscilloscopeC.Boot -> MainC;
        MultiHopOscilloscopeC.Timer -> TimerMilliC;
        MultiHopOscilloscopeC.Read -> Sensor;
        MultiHopOscilloscopeC.Leds -> LedsC;
        components CollectionC as Collector; /* Collection layer */
        ActiveMessageC; /* AM layer */
        new CollectionSenderC(AM_OSCILLOSCOPE); /* Sends multihop RF
        SerialActiveMessageC; /* Serial messaging */
        MultiHopOscilloscopeC.SerialControl -> SerialActiveMessageC;
        MultiHopOscilloscopeC.RootControl -> SerialActiveMessageC;
        MultiHopOscilloscopeC.RoutingControl -> Collector;
        MultiHopOscilloscopeC.Send -> CollectionSenderC;
        MultiHopOscilloscopeC.SerialSend -> SerialActiveMessageC.AMSend;
        MultiHopOscilloscopeC.Snoop -> Collector.Snoop(AM_OSCILLOSCOPE);
        MultiHopOscilloscopeC.Receive -> Collector.Receive(AM_OSCILLOSCOPE);
        MultiHopOscilloscopeC.RootControl -> Collector;
        components new PoolC(message_t, 10) as UARTMessagePoolP,
            new QueueC(message_t, 10) as UARTQueueP;
        MultiHopOscilloscopeC.UARTMessagePool -> UARTMessagePoolP;
        MultiHopOscilloscopeC.UARTQueue -> UARTQueueP;
        #include "Timer.h"
        #include "MultiHopOscilloscope.h"
        uses {
            /* Interfaces for initialization: */
            interface Boot;
            interface SplitControl as RadioControl;
            interface SplitControl as SerialControl;
            interface StdControl as RoutingControl;
            /* Interfaces for communication, multihop a serial: */
            interface Send;
            interface Receive as Snoop;
            interface Receive;
            interface AMSend as SerialSend;
            interface CollectionP;
            interface RootControl;
            interface QueueC as UARTQueue;
            interface PoolC as UARTMessagePool;
            /* Miscallany: */
            interface Timer<TMilli>;
            interface Read<uint16_t>;
            interface Leds;
        }

        /* Implementation: */
        task void uartSendTask() {
            static void startTimer();
            static void fatal_problem();
            static void report_problem();
            static void report_received();
            uint8_t uartlen;
            message_t sendbuf;
            message_t uartbuf;
            bool sendbusy=FALSE, uartbusy=FALSE;
            oscilloscope_t local;
            uint8_t reading; /* 0 to NREADINGS */
            bool suppress_count_change;
            event void Boot.booted() {
                local.interval = DEFAULT_INTERVAL;
                local.id = TOS_NODE_ID;
                local.version = 0;
                /* Beginning our initialization phases: */
                if (call RadioControl.start() != SUCCESS)
                    fatal_problem();
                if (call RoutingControl.start() != SUCCESS)
                    fatal_problem();
            }

            event void RadioControl.startDone(error_t error) {
                if (error != SUCCESS)
                    fatal_problem();
                if (sizeof(local) > call Send.maxPayloadLength())
                    fatal_problem();
                if (call SerialControl.start() != SUCCESS)
                    fatal_problem();
            }

            event void SerialControl.startDone(error_t error) {
                if (error != SUCCESS)
                    fatal_problem();
                /* This is how to set yourself as a root to the collection layer: */
                if (local.id % 500 == 0)
                    call RootControl.setRoot();
                startTimer();
            }

            static void startTimer() {
                if (call Timer.isRunning()) call Timer.stop();
                call Timer.startPeriodic(local.interval);
                reading = 0;
            }

            event void RadioControl.stopDone(error_t error) {
                event void SerialControl.stopDone(error_t error) {
                    event message_t*
                    Receive.receive(message_t* msg, void* payload, uint8_t len) {
                        oscilloscope_t* in = (oscilloscope_t*) payload;
                        oscilloscope_t* out;
                        if (uartbusy == FALSE) {
                            out = (oscilloscope_t*) SerialSend.getPayload(&uartbuf);
                            if (len != sizeof(oscilloscope_t))
                                return msg;
                            else {
                                memcpy(out, in, sizeof(oscilloscope_t));
                                out->len = sizeof(oscilloscope_t);
                                if (uartbusy == TRUE)
                                    return msg;
                                else {
                                    /* This is how to set yourself as a root to the collection layer: */
                                    if (local.id % 500 == 0)
                                        call RootControl.setRoot();
                                    startTimer();
                                }
                            }
                        }
                    }

                    event void SerialSend.sendDone(message_t* msg, error_t error) {
                        uartbusy = FALSE;
                        if (call UARTQueue.empty() == FALSE) {
                            message_t* queuemsg = call UARTQueue.dequeue();
                            if (queuemsg == NULL) {
                                fatal_problem();
                                return;
                            }
                            memcpy(&uartbuf, queuemsg, sizeof(message_t));
                            if (call UARTMessagePool.put(queuemsg) != SUCCESS) {
                                fatal_problem();
                                return;
                            }
                            post uartSendTask();
                        }
                    }

                    event message_t*
                    Snoop.receive(message_t* msg, void* payload, uint8_t len) {
                        oscilloscope_t* omsg = payload;
                        report_received();
                        /* If we receive a newer version, update our interval. */
                        if (omsg->version > local.version) {
                            local.version = omsg->version;
                            local.interval = omsg->interval;
                            startTimer();
                        }
                    }
                }
            }

            /* If we hear from a future count, jump ahead but suppress our own
            // change.
            if (omsg->count > local.count) {
                local.count = omsg->count;
                suppress_count_change = TRUE;
            }
            return msg;
        }

        event void timer.fired() {
            if (call Timer.isRunning()) {
                if (local.count < local.interval) {
                    local.readings[reading++] = (oscilloscope_t*) call Send.getPayload(&sendbuf);
                    if (call Send.send(&sendbuf, sizeof(local)) != SUCCESS)
                        report_problem();
                    else {
                        if (suppress_count_change == FALSE)
                            local.count++;
                        suppress_count_change = TRUE;
                    }
                }
                if (local.count > local.interval) {
                    if (suppress_count_change == FALSE)
                        local.count++;
                    suppress_count_change = TRUE;
                }
                if (local.count > local.interval) {
                    if (suppress_count_change == FALSE)
                        local.count++;
                    suppress_count_change = TRUE;
                }
                if (local.count > local.interval) {
                    if (suppress_count_change == FALSE)
                        local.count++;
                    suppress_count_change = TRUE;
                }
            }
        }

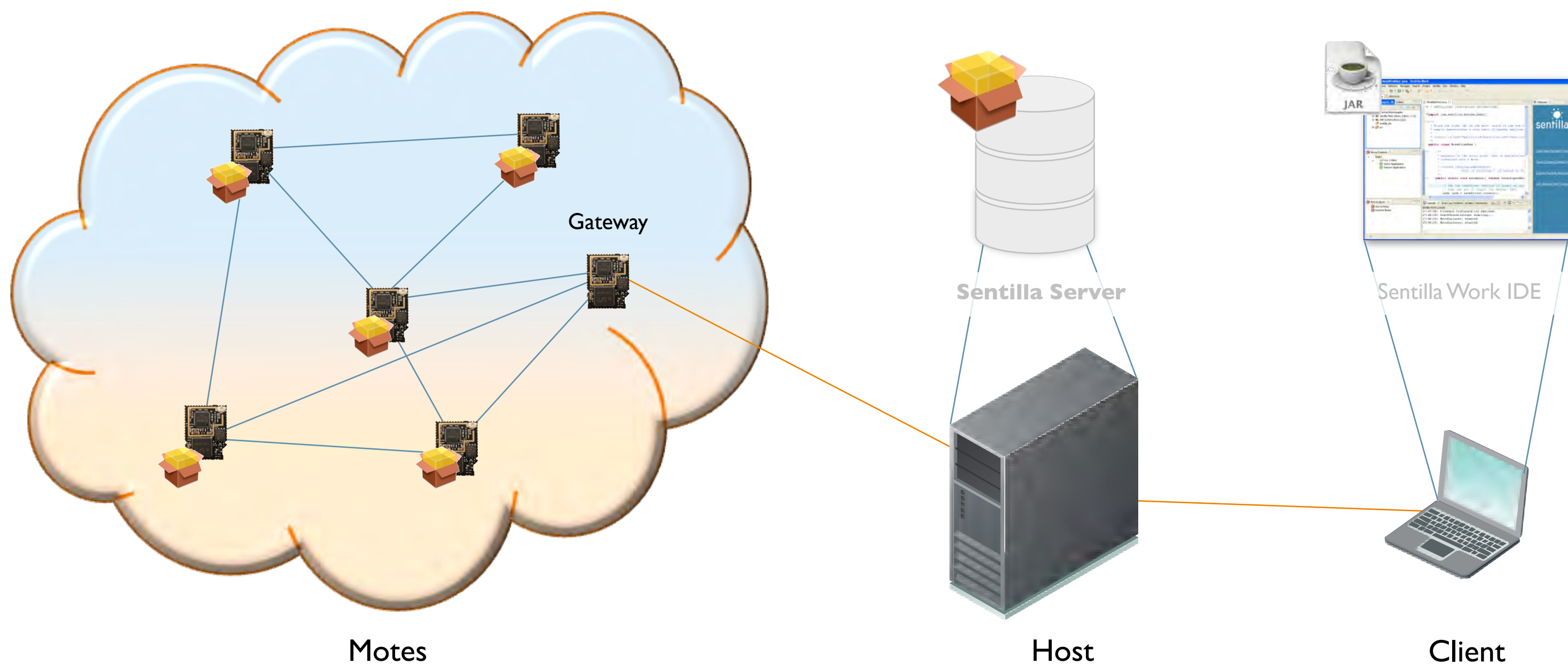
        event void Read.readDone(error_t result, uint16_t data) {
            if (result != SUCCESS) {
                data = 0xffff;
                report_problem();
            }
            local.readings[reading++] = data;
        }

        /* Use LEDs to report various status issues. */
        static void fatal_problem() {
            call Leds.led0On();
            call Leds.led1On();
            call Leds.led2On();
            call Timer.stop();
        }

        static void report_problem() { call Leds.led0Toggle(); }
        static void report_sent() { call Leds.led1Toggle(); }
        static void report_received() { call Leds.led2Toggle(); }
    }
}
```

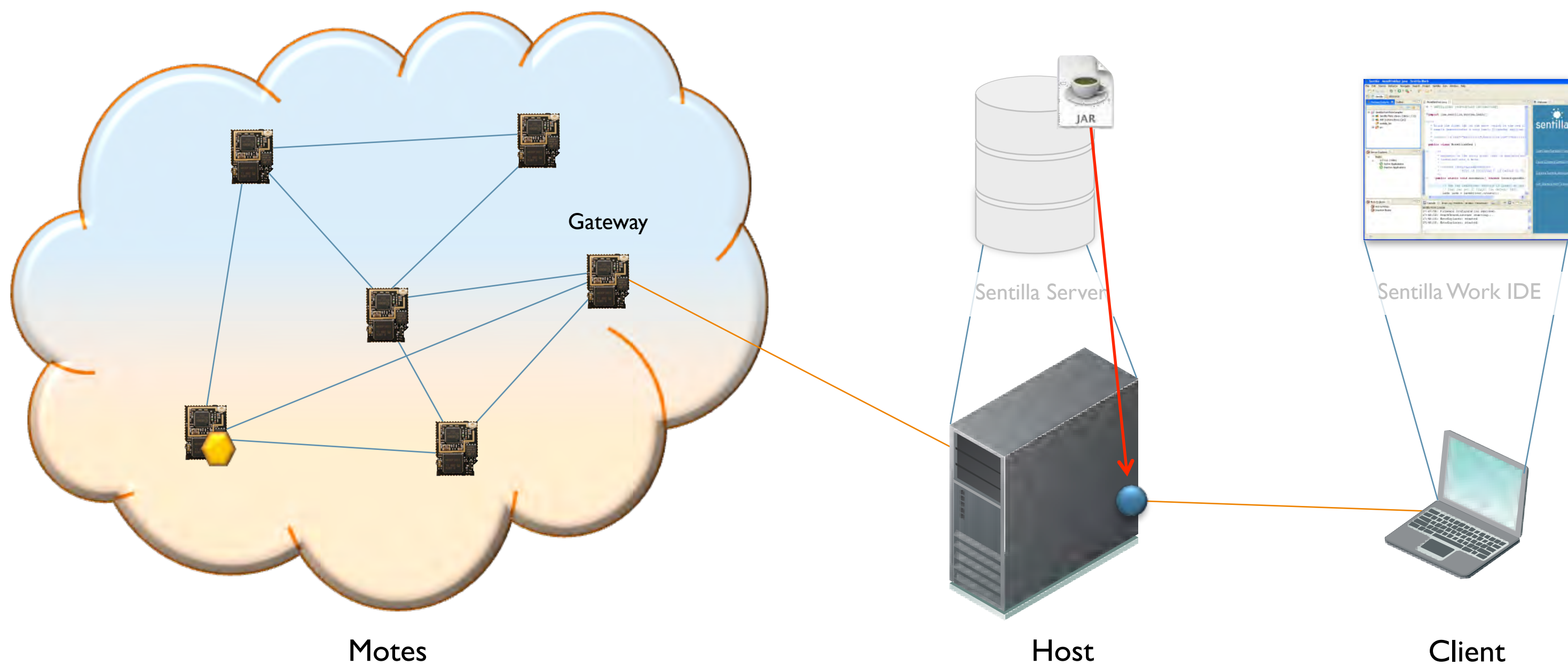


## Sentilla Application Distribution



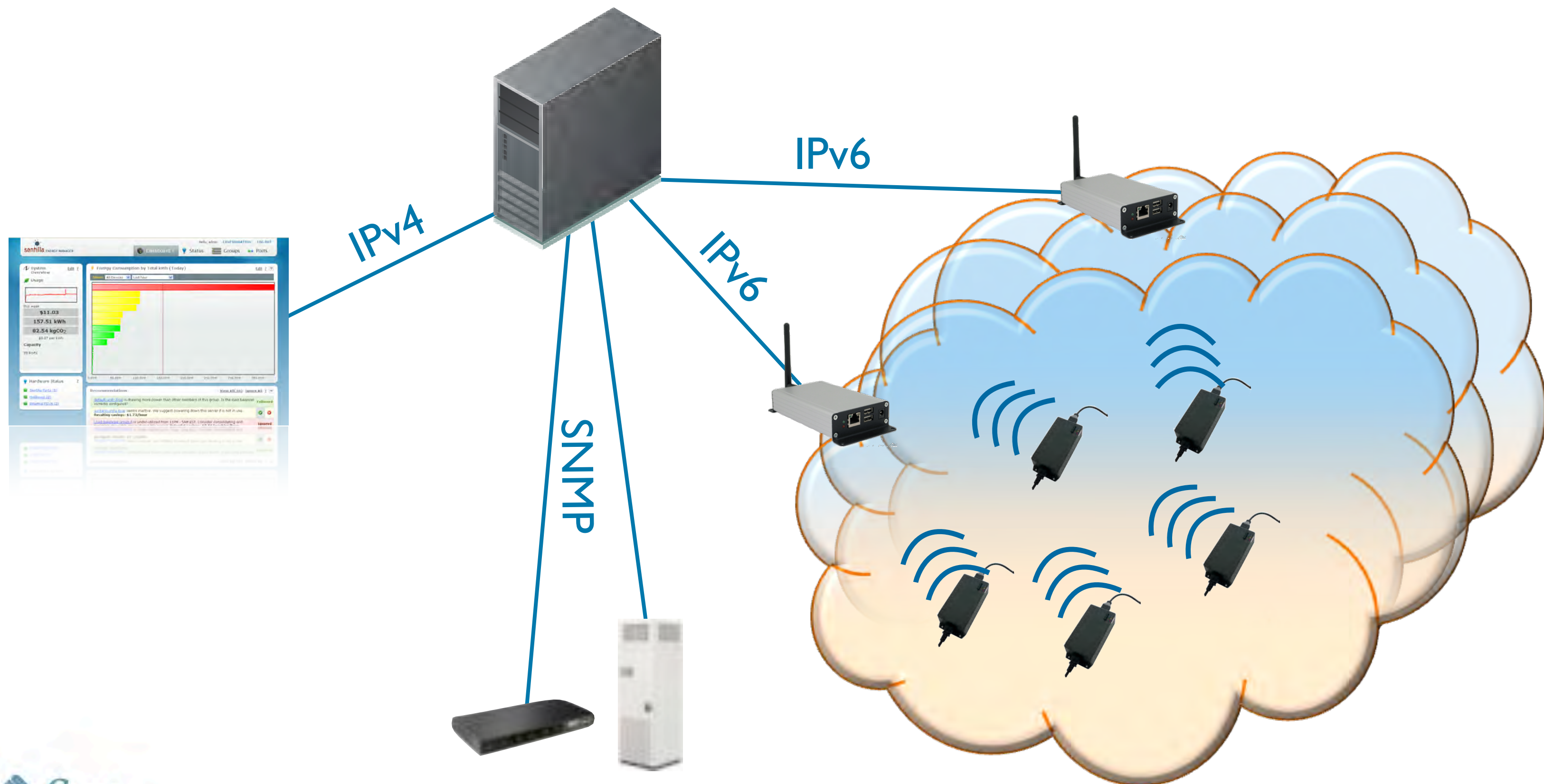


## Sentilla Application Distribution





# Architecture for Energy Management





## Low Power IP: 6lowpan

```
sender = (DatagramConnection) Connector.open("udp://[ff02::1]:" + ENERGY_PORT);  
receiver = (DatagramConnection) Connector.open("udp://:" + ENERGY_COMMAND_PORT);  
data = (Datagram) sender.newDatagram(100);  
rdata = (Datagram) receiver.newDatagram(100);
```

```
data.reset();  
data.setLength(100);  
emsg = new EnergyMessage();
```

```
emsg.clear();  
emsg.moteid = moteid;  
emsg.VRMS = meter.VRMS.read();  
emsg.IRMS = meter.IRMS.read();  
emsg.LA_ENERGY = meter.LA_ENERGY.read();  
emsg.LVA_ENERGY = meter.LVA_ENERGY.read();  
emsg.seqno++;  
sender.send(emsg.encode(data));
```

```
rdata.reset();  
receiver.receive(rdata);  
this.moteid = rdata.readLong();  
this.seqno = rdata.readLong();  
this.command = rdata.readByte();  
this.param = rdata.readInt();
```



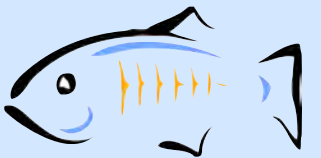
# Intelligent Energy Measurement

```
switch (dispatch) {  
    case Message.CAL_MSG:  
        setCalibration();  
        break;  
  
    case Message.COMMAND_MSG:  
        cmdmsg.decode(rdata);  
        doSwitch(cmdmsg.command);  
        break;  
    default:  
        break;  
}
```

```
switch(cmdmsg.command)  
{  
    case CommandMessage.CMD_SET_MODE:  
        Mode = ( byte)cmdmsg.param;  
        demo_stoptime = System.currentTimeMillis() * 1000 * 60;  
        break;  
    case CommandMessage.CMD_GET_CALIBRATION:  
        sender.block();  
        calmsg.send(sender,data);  
        break;  
    case CommandMessage.CMD_RESET:  
        meter.reset(( byte)0);  
        break;  
    case CommandMessage.CMD_SET_REPORT_RATE:  
        PollingPeriod = cmdmsg.param;  
        PropertyDriver.open( "P").writeInt(PollingPeriod);  
        break;  
    case CommandMessage.CMD_GET_REPORT_RATE:  
        cmdmsg.param = PollingPeriod;  
        cmdmsg.encode(data);  
        sender.block();  
        cmdmsg.send(sender,data);  
        break;  
    case CommandMessage.CMD_REINIT_ADE:  
        initADE();  
        break;  
}
```



- > Glassfish
- > Message Queue
- > Postgres
- > Django/Python
- > Apache



# Building an Energy Analysis EJB

```
package com.sentilla.bluebox.reclets.alerts;

import com.sentilla.bluebox.alerts.CurrentAlert;
import com.sentilla.bluebox.energy.entity.EnergyState;
import com.sentilla.bluebox.recommendation.interfaces.Reclet;
import java.io.Serializable;
import javax.ejb.ActivationConfigProperty;
import javax.ejb.MessageDriven;
import javax.jms.JMSException;
import javax.jms.Message;
import javax.jms.MessageListener;
import javax.jms.ObjectMessage;
import javax.persistence.EntityManager;
import javax.persistence.PersistenceContext;

@MessageDriven(mappedName = "EnergyManagerInputTopic", activationConfig = {
    @ActivationConfigProperty(propertyName = "acknowledgeMode", propertyValue = "Auto-acknowledge"),
    @ActivationConfigProperty(propertyName = "destinationType", propertyValue = "javax.jms.Topic"),
    @ActivationConfigProperty(propertyName = "subscriptionDurability", propertyValue = "Durable"),
    @ActivationConfigProperty(propertyName = "clientId", propertyValue = "AlertBean"),
    @ActivationConfigProperty(propertyName = "subscriptionName", propertyValue = "AlertBean")
})
```



```

public class SampleCurrentAlert implements MessageListener, Reclet {
    private static int THRESHOLD = 140;
    @PersistenceContext(unitName = "SampleCurrentAlertPU")
    private EntityManager em;

    public void onMessage(Message message) {
        if (message instanceof ObjectMessage) {
            Serializable objmsg = null;
            try { objmsg = ((ObjectMessage)message).getObject();
            } catch (JMSException ex) {
                ex.printStackTrace();
            }

            if (objmsg instanceof EnergyState) {
                EnergyState emsg = (EnergyState) objmsg;
                if (emsg.getIRMS() > THRESHOLD) {
                    CurrentAlert alert = new CurrentAlert();
                    alert.setNodeId(emsg.getMoteId());
                    alert.setMessage("Max current threshold exceeded");
                    em.persist(alert);
                }
            }
        }
    }
}

```



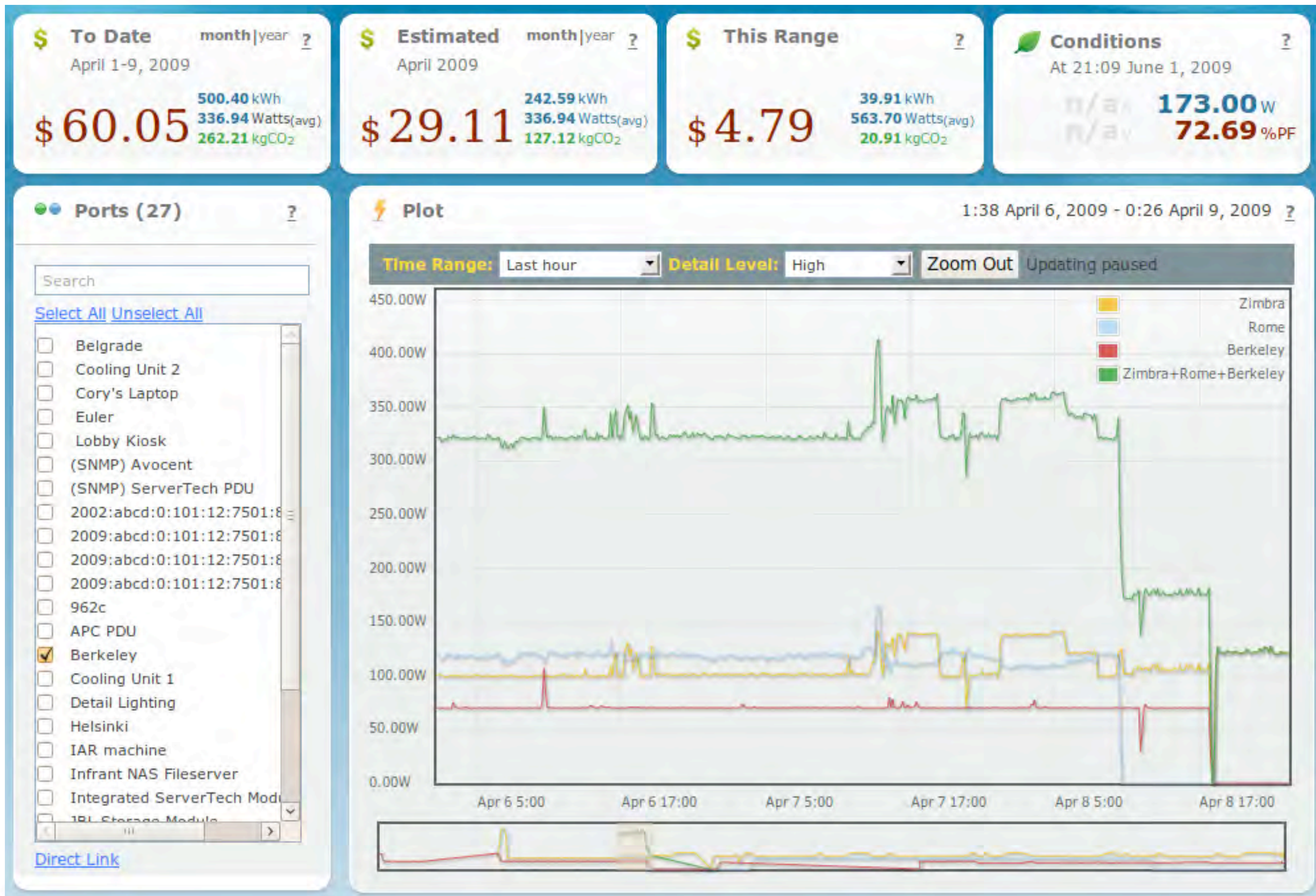


**Datacenters use  
1.5% of the world's electricity**



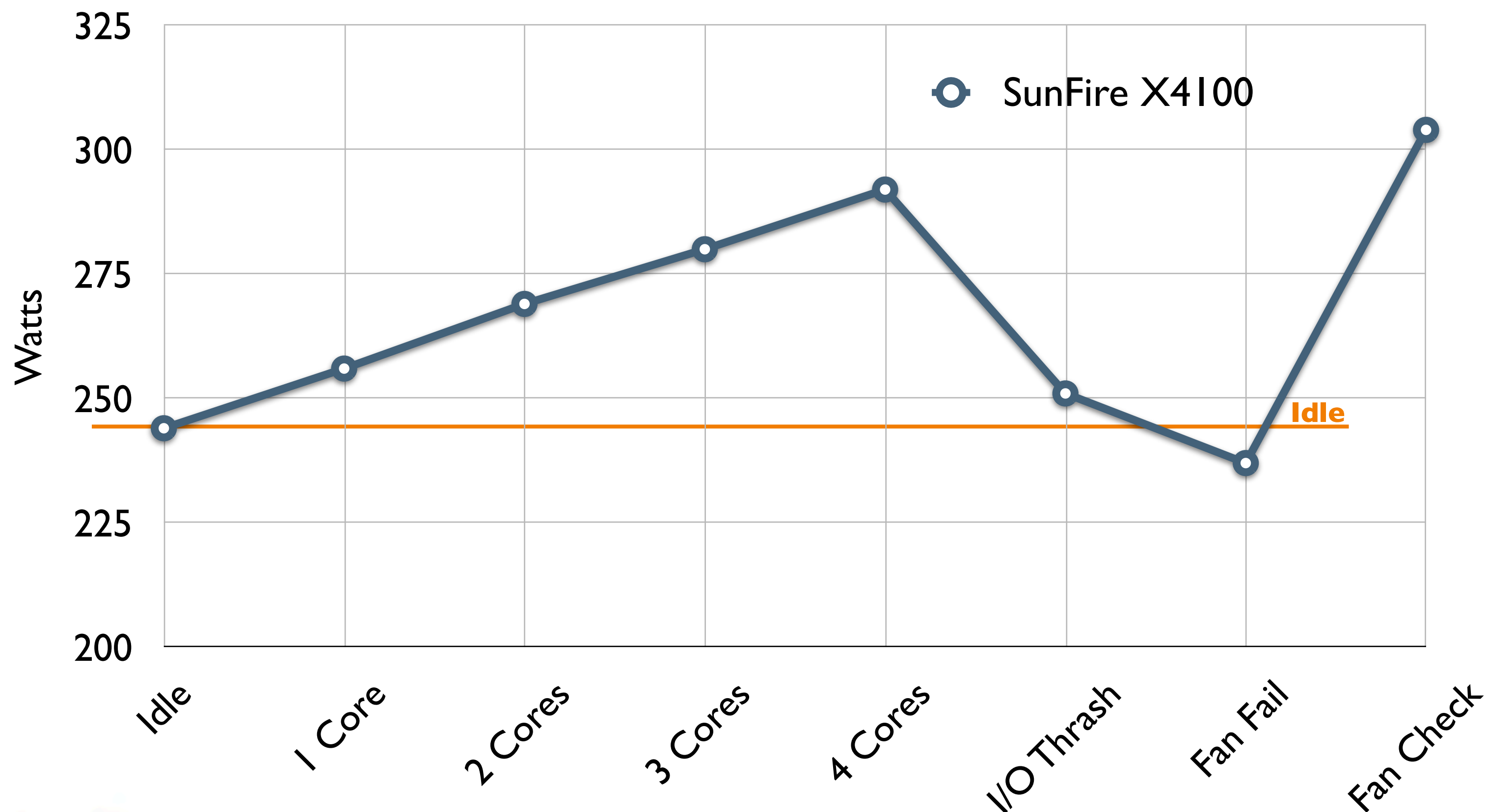


## Demo

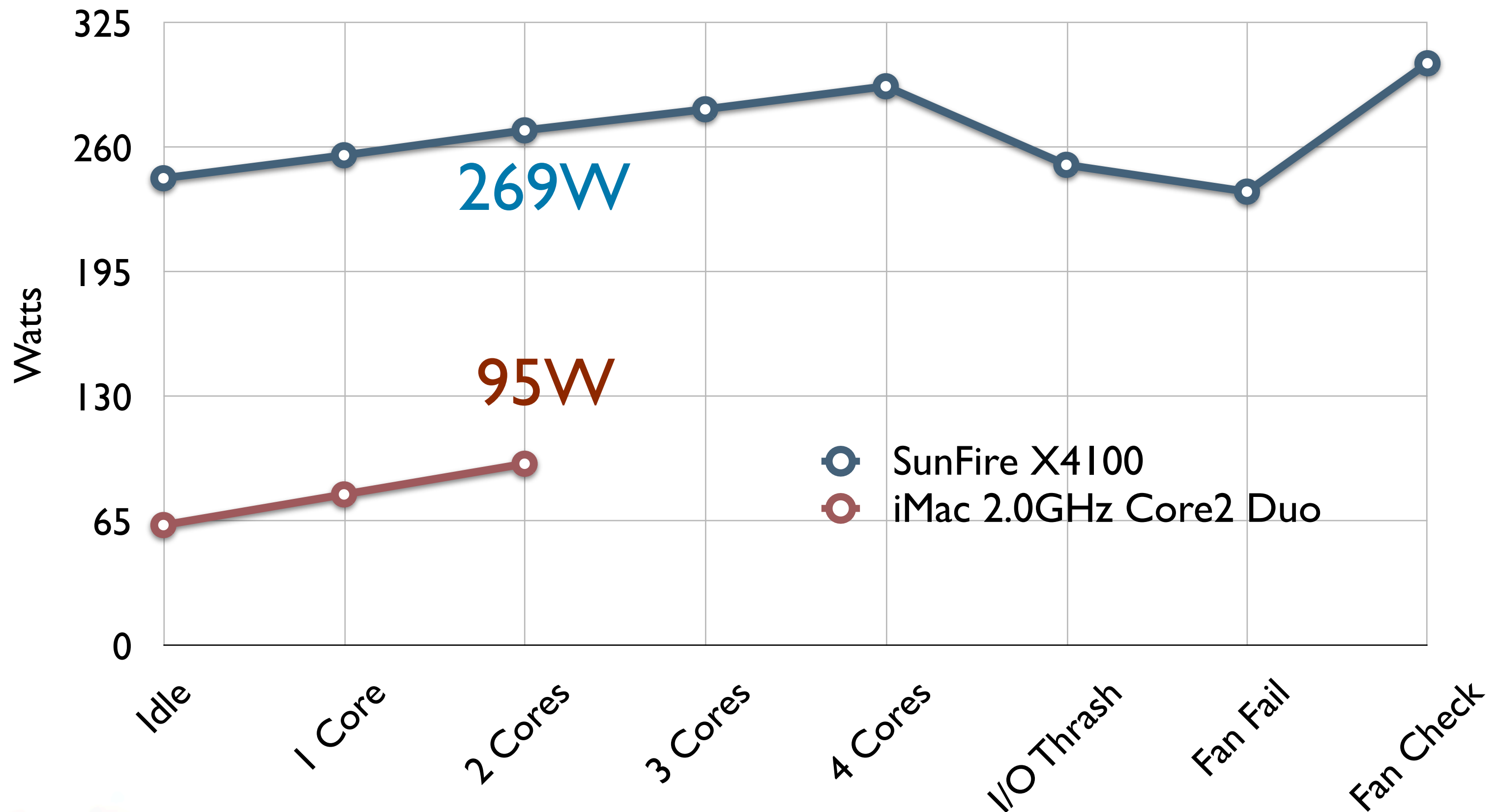




# Real-time Energy Profiling



# Energy Comparison





# Floating Point Comparison

	Idle Watts	Active Watts	SPECfp2006	Watt/fp
SunFire	244	269	14.7	18.3
iMac	63	95	8.8	10.8

SPECfp2006 is relative to a Sun UltraSparc II system at 296MHz



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Computer	12.2 Kwh	\$1.40
Clothes Dryer	35.2 Kwh	\$4.05
Not Controlled	59.0 Kwh	\$6.79



# The Internet is Lonely

(and so is the thermostat)



**570 million things on the Internet**

**10+ trillion things in the world**

**0.005% of things on the Internet**







# JavaOne<sup>SM</sup>

# Thank You



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